## E124

## green opro Dea 2easy

## IT

QUICK GUIDE - istruzioni di collegamento e programmazione dell'apparecchiatura per la messa in funzione di un impianto tipo (per le illustrazioni fare riferimento allinserto centrale). Le istruzioni complete devono essere scaricate dal sito www.faacgroup.com.

## EN

QUICK GUIDE - equipment connection and programming instructions for operating a standard system (refer to the middle for the pictures collection). Complete instructions must be downloaded from the web sitewww.faacgroup.com.

## FR

QUICK GUIDE - instructions pour la connexion et la programmation de la platine pour la mise en fonction d'une installation type ( pour les illustrations se référer à la collection de figures central). Les instructions complètes doivent être téléchargées du site web www.faacgroup.com.

## DE

QUICK GUIDE - Anweisungen für den Anschluss und die Programmierung des Geräts zur Inbetriebnahme einer Standardanlage (die Illustrationen finden Sie in der Mitte des Handbuchs). Die vollständigen Anweisungen müssen von der Website www.faacgroup.com heruntergeladen werden.

## ES

QUICK GUIDE - instrucciones de conexión y programación del equipo para la puesta en funcionamiento de una instalación tipo (para las imagenes remítase al anexo central). Las instrucciones completas deben descargarse del sitio web www.faacgroup.com.

## NL

QUICK GUIDE - instructies voor de aansluiting en programmering van de apparatuur voor de inbedrijstelling van een standaardinstallatie (raadpleeg de inzet in het midden voor de afbeeldingen). De volledige instructies moeten van de website www.faacgroup.com worden gedownload.


## WARNINGS

- Important! For the safety of people, it is important that all the instructions be carefully observed.
- Incorrect installation or incorrect use of the product could cause serious harm to people.
- Carefully read the instructions before beginning to install the product and keep them for future reference.
- The symbol indicates notes that are important for the safety of persons and for the good condition of the automated system.
- The symbol draws your attention to the notes on the characteristics and operation of the product.
- Before attempting any work on the control unit (connections, maintenance), always turn off power.
- Install, upstream of the system, a differential thermal breaker with adequate tripping threshold,
- Connect the earth cable to the relevant terminal.
- Always separate power cables from control and safety cables (push-button, receiver, photocells, etc.). To avoid any electrical disturbance, use separate sheaths or a screened cable (with the screen earthed).


## EU DECLARATION OF CONFORMITY

The Manufacturer

## Company name:

FAAC S.p.A. Soc. Unipersonale
Address: Via Calari, 10-40069 Zola Predosa BOLOGNA - ITALIA
hereby declares under its own exclusive liability that the following product:

| Description: | Control board |
| :--- | :--- |
| Model: | E124 |

complies with the following applicable EU legislations:
Furthermore, the following harmonised standards have been applied: EN61000-6-2:2005, EN61000-6-3:2007 + A1:2011
Bologna, 10/1/2018 CEO
A. Marcellan


TECHNICAL SPECIFICATIONS

| Primary power feed from mains | with switching power feed 230/115 V~-50/60 Hz |
| :---: | :---: |
| Secondary power feed | $24 \mathrm{~V}=-16 \mathrm{~A}$ max. (min. $20 \mathrm{~V}==$. - max. $28 \mathrm{~V}=$ =- . |
| Power absorbed from mains | stand-by $=4 \mathrm{~W}$ max. $\sim 400 \mathrm{~W}$ |
| Max. load for motor | 7 A |
| Power feed for accessories | $24 \mathrm{~V}=$ |
| Accessories max. current | $24 \mathrm{~V}=-\mathrm{max} .500 \mathrm{~mA}$, BUS-2EASY max. 500 mA |
| Battery charge current | 180 mA |
| Operating ambient tempeature | $(-20-+55)^{\circ} \mathrm{C}$ |
| Protective fuses for unit | All self resetting |
| Protective fuses for power pack | 2.5 A |
| Function logics | Semiautomatic, Automatic, "step-by-step" Semiautomatic, Automatic with reverse during pause, Automatic step-by-step, Safety devices automatic, Safety devices step-by-step automatic, "b" Semiautomatic, mixed logic "bC", Dead-man, Automatic with timer function |
| Work time | Programmable (from 0 to 9 min 50 sec ) |
| Pause time | Programmable (from 0 to 9 min 50 sec ) |
| Motor power | Programmable on 50 levels |
| Motor speed | Programmable on 10 levels |
| Connector inputs | Switching feeder, Battery, Decoder/Minidec/RP, X-COM, module XF433/868, USB |
| Terminal board inputs | BUS-2EASY, Inputs from IN1 to IN5, Travel limit device, Encoder. |
| Terminal board outputs | Flashing lamp, Motors, Electrical lock, OUT1, OUT2 (programmable), power feed to accessories |
| Programming | 1st and 2nd lev. with 3 keys (+, -, F) and LCD display./ 3rd lev. with PC connected via USB |

- These instructions are to be considered as a rapid guide for installation. The complete instructions can be downloaded at the following address: www.faacgroup.com
To access PROGRAMMING FROM PC/MAC, connect the USB cable to the dedicated connector and consult the relative instructions.


## FAAC

LAYOUT AND COMPONENTS OF E124 BOARD


| DESCRIPTION OF COMPONENTS |  |  |  |
| :---: | :---: | :---: | :---: |
| LCD | SIGNALSAND PROGRAMMING DISPLAY | DL16 | LED FOR "SW1" PUSH-BUTTON (R1 PUSH-BUTTON) |
| SW1 | "R1" PROGRAMMING PUSH-BUTTON | DL17 | LED FOR "SW2" PUSH-BUTTON (R2 PUSH-BUTTON) |
| SW2 | "R2" PROGRAMMING PUSH-BUTTON | DL18 | LED FOR "SW3" PUSH-BUTTON (SETUP PUSH-BUTTON) |
| SW3 | "SETUP" PUSH-BUTTON | DL19 | PRESSURE SIGNALLING LED "RESET SW" PUSH-BUTTON |
| SW4 | "+" PROGRAMMING PUSH-BUTTON | DL20 | ALARM SIGNALLING LED "ALARM" |
| SW5 | "-" PROGRAMMING PUSH-BUTTON | J1 | POWER FEEDER SWITCHING CONNECTOR |
| SW6 | "F"PROGRAMMING PUSH-BUTTON | J2 | SECONDARY POWER SELECTOR |
| SW7 | "RESET SW' SOFTWARE RESET PUSH-BUTTON | J3 | CONNECTOR FOR CONNECTION TOBUS-2EASY DEVICES |
| DL1 | INPUTSTATUS CONTROLLED "IN1" | J4 | CONNECTOR FOR TERMINAL BOARD INPUTS |
| DL2 | INPUTSTATUS CONTROLLED "IN2" | J5 | CONNECTOR FOR OUT2 OUTPUT (see 2nd level prog.) |
| DL3 | INPUTSTATUS CONTROLLED "IN3" | J6 | TRAVEL LIMITS CONNECTOR |
| DL4 | INPUTSTATUS CONTROLLED "IN4" | J7 | CONNECTOR FOR LEAF 1 AND LEAF 2 ENCODER INPUTS |
| DL5 | INPUTSTATUS CONTROLLED "IN5" | J8 | CONNECTOR FOR OUT1 OUTPUT (see 2nd level prog.) |
| DL6 | INPUTSTATUS CONTROLLED "FCA1" | J9 | FLASHING LAMP OUTPUTCONNECTOR |
| DL7 | INPUTSTATUS CONTROLLED "FCC1" | J10 | CONNECTORFORELECTRICALLOCK OUTPUT |
| DL8 | INPUTSTATUS CONTROLLED "FCA2" | J11 | LEAF 1 MOTOR CONNECTOR |
| DL9 | INPUT STATUS CONTROLLED "FCC2" | J12 | LEAF 2 MOTOR CONNECTOR |
| DL10 | INPUT STATUS CONTROLLED "ENC1" (Gatecoder) | J13 | CONNECTOR FOR RECEIVER MODULE XF433/XF868 |
| DL11 | INPUT STATUS CONTROLLED "ENC2" (Gatecoder) | J14 | CONNECTOR: DECODER/MINIDEC/RP RECEIVER |
| DL12 | LED FOR DEVICE BUS-2EASYACTIVE | J15 | USB CONNECTORFOR PROGRAMMING FROM PC |
| DL13 | LED FOR BUS-2EASY DIAGNOSTICS | M1A | ACCESSORIES MODULE CONNECTOR |

POWER FEED


J1: Select the correct power feed, by turning the power switching selector to its correct position (Default $230 \mathrm{~V} \sim$ )

To ensure correct operation, the switching feeder must be connected to the earth conductor in the system. Install an adequate differential thermal breaker upstream of the system.

## SECONDARY POWER FEED

J2: In the absence of a primary feed from the mains, the control unit can be fed by a secondary low voltage ( $24 \mathrm{~V}=-=$ ) power feed. Power can be supplied by a pack of batteries, recharged by a battery charger integrated in the board, or by a stabilised power feeder. In both cases, the power supply must have the following characteristics:

> Voltage: $(24 \pm 4) \mathrm{V}=-$
> Current: 16 A max.

If you use an external stabilised feeder, you must disable the "battery charger" function via the PC (see dedicated instructions).

## INPUTS DEFAULT SETTING

Terminal-board J4

| IN1 | OPEN A | N.O. contact |
| :--- | :--- | :--- |
| IN2 | OPEN B | N.O. contact |
| IN3 | STOP | N.C. contact |
| IN4 | FSW OP | N.C. contact |
| IN5 | FSW CL | N.C. contact |

Connector J13 - XF Module (OMNIDEC)

| Channel 1 | OPEN A |
| :--- | :--- |
| Channel 2 | OPEN B |

## Connector J14 - Radio

| Channel 1 RP | OPEN A |
| :--- | :--- |
| Channel 2 RP2 | OPEN B |

## TERMINAL BOARD MOTORS

J11 (MOT1): Connection of motor connected to leaf 1, i.e. the leaf which opens first during an opening operation.
J12 (MOT2): Connection of the motor connected to leaf 2, i.e. the leaf which opens second.

If only one motor is connected, it must be connected to terminal J11 (MOT1).

If, during the first movement of the SETUP procedure, the leaves open instead of closing, the motor connection cables must be changed over.

## LED OPERATION

| LED | Description | ON (contact closed) | OFF <br> (contact open) |
| :---: | :---: | :---: | :---: |
| DL1 | IN1 OPENA | Command enabled | Command disabled |
| DL2 | IN2 OPENB | Command enabled | Command disabled |
| DL3 | $\begin{aligned} & \hline \text { IN3 } \\ & \text { STOP } \end{aligned}$ | Command disabled | Command enabled |
| DL4 | $\begin{aligned} & \text { IN4 } \\ & \text { FSW OP } \end{aligned}$ | Safety devices disabled | Safety devices tripped |
| DL5 | IN5FSWCL | Safety devices disabled | Safety devices tripped |
| DL6 | FCA1 | Opening travel-limit devices free | Opening travel-limit devices engaged |
| DL7 | FCC1 | Closing travel-limit devices free | Closing travel-limit devices engaged |
| DL8 | FCA2 | Opening travel-limit devices free | Opening travel-limit devices engaged |
| DL9 | FCC2 | Closing travel-limit devices free | Closing travel-limit devices engaged |
| DL10 | ENC1 | Flashing during operation (Gatecoder) |  |
| DL11 | ENC2 | Flashing during operation (Gatecoder) |  |
| DL12 | SIGNALLING LED FOR DEVICE BUS-2EASY ACTIVE |  |  |
| DL13 | SIGNALLING LED FOR BUS-2EASY DIAGNOSTICS |  |  |
| DL14 | LED SIGNALLING PRIMARY POWER ON |  |  |
| DL15 | LED SIGNALLING SECONDARY POWER ON |  |  |
| DL16 | LED FOR "SW1" PUSH-BUTTON (R1 PUSH-BUTTON) |  |  |
| DL17 | LED FOR "SW2" PUSH-BUTTON (R2 PUSH-BUTTON) |  |  |
| DL18 | LED FOR "SW3" PUSH-BUTTON (SETUP PUSH-BUTTON) |  |  |
| DL19 | LED "RESET SW" PUSH-BUTTON |  |  |
| DL20 | ALARM SIGNALLING LED "ALARM" |  |  |

Flashing LED ALARM indicates alarm in progress (a situation which does not prejudice gate operation)

LED ALARM on steady light indicates error in progress (a situation which blocks operation until cause of error is eliminated)

## ELECTRICAL CONNECTIONS



## CONNECTION OF TRADITIONAL SAFETY DEVICES

With the E124 control unit, you can use both traditional photocells (N.C. contact with relay) and/or photocells with BUS-2EASY.


Connection of a pair of closing photocells and a pair of opening/closing photocells with disabled FAIL-SAFE safety device and STOP
IN4 ${ }^{\text {GND }}{ }_{\text {IN5 }}{ }^{+24}$
12345678 J 4


## PHOTOCELLS BUS-2EASY

## ADDRESSING THE BUS-2EASY PHOTOCELLS

Important: the same address must be given to both transmitter and receiver.
Make sure that there are not two or more photocell pairs with the same address.

If you are not using any BUS-2EASY accessory, leave free connector BUS-2EASY

The following table shows the programming operations of the dip-switch inside the transmitter and the BUS-2EASY photocells receiver.


| Dip1 | Dip2 | Dip3 | Dip4 | Rif. | Type |
| :---: | :---: | :---: | :---: | :---: | :---: |
| OFF | OFF | OFF | OFF | B - C | OPENING |
| OFF | OFF | OFF | ON |  |  |
| OFF | OFF | ON | OFF |  |  |
| OFF | OFF | ON | ON |  |  |
| OFF | ON | ON | OFF |  |  |
| OFF | ON | ON | ON |  |  |
| ON | OFF | OFF | OFF | D | CLOSING |
| ON | OFF | OFF | ON |  |  |
| ON | OFF | ON | OFF |  |  |
| ON | OFF | ON | ON |  |  |
| ON | ON | OFF | OFF |  |  |
| ON | ON | OFF | ON |  |  |
| ON | ON | ON | OFF |  |  |
| OFF | ON | OFF | OFF | A | OPENING and CLOSING |
| OFF | ON | OFF | ON |  |  |
| ON | ON | ON | ON | / | OPEN PULSE |

## BUS-2EASY ENCODER CONNECTION

- 융 Leaf 1 opens as first and closes as second


1. Connect the 2 encoder cables to the BUS-2EASY input (red terminal) on the board.
2. Check that the encoder is connected correctly according to the table. The LEDs must be checked with the leaf stopped
Absolute encoder

If necessary, swap the 2 connecting wires to obtain the correct coupling of the encoder with the leaf as indicated in the following figure.


## Connector J13 - XF MODULE rapid connection



The control unit has an integrated 2-channel decoding system (DS, SLH, LC/RC) named OMNIDEC. This system makes it possible to save - through an extra receiver module - XF433 or XF868 radio commands of the same frequency, but of a different type (DS, SLH, LC/RC). It is possible to save both total opening (OPEN A) and partial opening (OPEN B) of the automated system, up to a maximum of 256 channels.

## Insert and remove the boards only after cutting power.

## PROGRAMMING

Programming is divided in two levels:

- BASIC programming
- ADVANCED programming

The programming phases are (see Tab.):

1. to access PROGRAMMING (1A or 1B);
2. to show the set values and modify them, if you want. Changing the values is effective immediately, while the final memorisation must be carried out upon exiting programming (らレ) ).
3. exit the programming by using 5 Lunction. Select $\unlhd$ to SAVE the configuration you just performed, otherwise select $\cap \square$ to EXIT WITHOUT SAVING any changes.

You can EXIT programming at anytime:

- press and hold $\mathbf{F}$ and then also - to switch directly to 5 L


This board also allows programming using a PC or MAC.
This programming requires connection to PC/MAC via USB cable and USB-B relevant port.
The programming SOFTWARE with relevant instructions, must be downloaded from the website:
www.faacgroup.com
The programming using a PC/MAC, with the default PASSWORD does not inhibit the programming by board. The writing P[ will be displayed in correspondence with the modified values. Notes: when you modify the values by board the previous PC/MAC programming will be overwrote.

## The default password is 0000 .

The programming using a PC/MAC, with a modified PASSWORD (different from the default one), will inhibit the programming by board. If one of the buttons is pressed, the display will show $P[$ programming for 5 sec and changes will be allowed only by PC/MAC.


BASIC PROGRAMMING

| Display | Basic Function | CF |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\square$ | 1 | コ | 4 | $\exists$ | E | 5 |
| ロF | （－）Configures the parameters with DEFAULT values corresponding to an installation with non－FAAC operators．（see column cF 0）． <br> Configures the parameters with DEFAULT values corresponding to an installation with operators FAAC 412，413／415，770，390， 770N（see column cif 1）． <br> ᄅ Configures the parameters with DEFAULT values corresponding to an installation with operators FAAC 391 （see column ciF 2）． <br> $\exists \quad$ Configures the parameters with DEFAULT values corresponding to an installation with operators FAAC S700H／S800H（see column \＆F 3）． <br> 4 Configures the parameters with DEFAULT values corresponding to an installation with operators FAAC 418．（see column cF 4）． <br> $5 \quad$ Configures the parameters with DEFAULT values corresponding to an installation with operators FAAC S450H（see column of 5）． <br> E Configures the parameters with DEFAULT values corresponding to an installation with operators FAAC S800H ENC（see column cF 6）． <br> P［－Mixed configuration from a PC／MAC <br> －웅 <br> At the time of changing the set motor type on the board， the relevant defaults are uploaded． | $\square$ | 1 | コ | 4 | $\exists$ | E | $\square$ |
| ㄴII | DEFAULT： <br> U indicates that all the set values correspond to the default values． <br> no indicates that one or more set values are different from the de－ fault． <br> Set $\zeta$ if you want to restore the default settings． | Ч |  | － |  |  |  | － |
| \＆ | FUNCTION LOGICS： <br> E Semi－automatic <br> EP Semi－automatic Step－by－Step <br> G Automatic Safety Devices <br> 5 A Automatic with reversal during pause <br> 5．P Automatic Step－by－Step Safety Devices <br> Al Automatic 1 <br> A Automatic <br> AP Automatic Step－by－Step <br> FIt Automatic timer <br> b Semi－automatic＂b＂ <br> b－Mixed（Pulses for opening／Dead－man commands for closing） <br> ［ Dead－man <br> ［L Logic modified from a PC／MAC <br> Other more detailed programming possibilities are feasible by programming with a PC（see dedicated instructions）． | $E$ |  | $E$ |  |  |  | $E$ |


| Display | Basic Function | cF |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 0 | 1 2 | 4 | $\exists \mathrm{E}$ | 5 |
| PF | PAUSE TIME A（visualised only if the selected logic allows automatic reclosing）： Pause time following a TOTAL opening command．It has only effect if a logic with pause time was selected．Can be adjusted from 0 to 59 sec ． in one－second steps． <br> Next，the viewing changes in minutes and ten seconds（separated by a dot）and time is adjusted in 10－second steps，up to the maximum value <br> dot）and time is a of 9.5 minutes． <br> E．g．：if the display shows ᄅ．5，the pause time will be 2 min ．and 50 sec ． | $\exists \square$ | $\exists 1$ |  | $3 \square$ | ヨロ |
| Pb | PAUSE TIME B（visualised only if the selected logic allows automatic reclosing）： <br> Pause time following a PARTIAL opening command．It has only effect if a logic with pause time was selected． | $\exists \square$ | $\exists 10$ |  | ヨロ | $\exists \square$ |
| Mn | NR．OF MOTORS： <br> You can select the number of motors present in the system： <br> $=1$ motor <br> $=2$ motors <br> If the SETUP is performed with only one motor，and later two motors are used，the board will signal error｜ㅂ－con－ figuration error，which can be deleted by repeating the SETUP with two motors or by returning to one motor． If a SETUP is performed with two motors and later only one is used，the board will not signal an error．Only the motor connected to input M1 will move． <br> When programming from a PC／MAC，you can select different partial openings． | Q2 | $\square 2$ |  | $\square 2$ | 02 |
| FI | MOTOR 1 POWER <br> You can adjust the maximum power of motor 1 ，which is the same during <br> both opening and closing． <br> 미＝minimum power <br> 50＝maximum power <br> IS웅 If the power is modified，we recommend performing a new SETUP－see the related paragraph． <br> 군 Other more detailed programming possibilities are feasible by programming with a PC（see dedicated instructions）． | こち | 25 |  | 415 | $\exists 5$ |
| F2 | MOTOR 2 POWER（visualised only with the function $\Pi$ П＝こ）： You can adjust the maximum power of motor 2 ，which is the same during both opening and closing | こち | $こ 5$ |  | 415 | $\exists 5$ |
| 5 | SPEED： <br> Adjusts the motion speed of the motors．There are 10 levels．The value is relative and not absolute，because the speed value refers to the weight of the leaf measured during the SETUP cycle <br> —1＝minimum speed <br> $1 \square$＝maximum speed <br> 중 Other more detailed programming possibilities are feasible by programming with a PC（see dedicated instructions） | 01 | 018 |  | 08 | 08 |


| Display | Basic Function | CF |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\square$ | 1 | 己 | 4 | $\exists$ | G | 5 |
| Er | ENCODER USE： <br> You can enable／disable the use of encoders（both BUS and GATECODER encoders）： <br> 〕＝encoders on both motors <br> $\mathrm{n口} \mathrm{=} \mathrm{encoders} \mathrm{disabled}$ <br> When using configurations $\exists, 5$ or $Б$ <br> it is mandatory to use the encoder，$\cap \square$ is not selectable | 「ロロ |  | 「ル｜ |  |  |  | － |
| $F$ F | LIMIT SWITCH WHEN OPENING： <br> Lets you set or disable use of the opening limit switch on swing－leaves． <br> no＝opening limit switches disabled <br> 이＝the limit switch determines the stopping of motion <br> $02=$ the limit switch determines the start of deceleration <br> －3 After having changed the value of this function，SETUP is required：the card will signal error ${ }^{4} \mid$（configuration error） until the SETUP is performed again or until the previous value is restored | ワロロ |  | 「ル｜ |  |  |  | ワル｜ |
| FI－ | LIMIT SWITCH WHEN CLOSING： <br> Lets you set or disable use of the closing limit switch on swing－leaves． <br> n口＝closing limit switches disabled <br> OI＝the limit switch determines the stopping of motion <br> O2＝the limit switch determines the start of deceleration <br> － Sis $_{3}$ After having changed the value of this function，SETUP is required：the card will signal error ${ }^{14}$（configuration error） until the SETUP is performed again or until the previous value is restored． | トロー |  | 「ルロ |  |  |  | ヤレロ |
| E－ | DELAY FOR CLOSING LEAF（visualised only with the function Пin ＝ᄅ）： <br> Is the delay time for starting leaf 1 closing with respect to leaf 2．Makes it possible to avoid overlapping of the two leaves． Adjustable from to 59 sec ，in 1 －second steps． <br> Next the value 59，the viewing changes to minutes and tenths of a second （separated by a decimal point）and time is adjusted in 10 －second steps up to the maximum value of $\exists$ minutes． <br> e．g．：if the display shows 1. ．ᄅ，the time is 1 min and 20 sec | ■ |  | 「1年 |  |  |  | －15 |
| レاー！ | BUS－2EASY DEVICES ENTRY： <br> See the related paragraph． | トロロ |  | 「ルロ |  |  |  | ヤレロ |


| Display | Basic Function | CF |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\square$ | 1 | コ | 4 | $\exists$ | E | 5 |
| 「マ1 | MOTOR 2 dead－man DRIVE mode（visualised only with the function $\Pi \square=$ ） OPENS（visualising $\square^{\square}$ ）until the button is held down CLOSES（visualising－L ）until the button is held down | －－ |  | －－ |  |  |  | －－ |
| F1］ | MOTOR 1 dead－man DRIVE mode OPENS（visualising $\square^{P}$ ）until the button is held down CLOSES（visualising ᄃL ）until the button is held down | －－ |  | －－ |  |  |  | －－ |
| 上亡 | WORK TIME LEARNING（SETUP）： <br> See the related paragraph． | －－ |  | －－ |  |  |  | －－ |
| 「吅 | AUTOMATED SYSTEM STATUS： <br> You can exit programming，choosing whether or not to save the configuration you just performed． <br> 1．set the choice： <br> $\unlhd$ to SAVE and EXIT the programming <br> ח口 to EXIT the programming WITHOUT SAVING <br> 2．press the button $\mathbf{F}$ to confirm；at the end the display returns to visualize the automated system status： <br> WARNING If power is lost to the board prior to confirmation（step 2．），all changes made will be lost． <br> You can EXIT programming at any time：press and hold $\mathbf{F}$ and then also $\mathbf{=}$ to switch directly to 5 L． |  |  |  |  |  |  | － |

ADVANCED PROGRAMMING

| Display | Advanced Function | ■ |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 11 | ■ | － | ב | ■ | ■ |
| ■1I | TIME OF MAXIMUM POWER AT STARTING： <br> You can set the starting time．During start the motors work at maximum power for starting the movement． <br> Adjustable from to 10 sec，in 1 －second steps（ignoring the power level selected with $F \mid$ and $F \stackrel{\text { I }}{ }$ ）． <br> Other more detailed programming possibilities are feasible by programming with a PC（see dedicated instructions）． | 11二 | [1: |  | [1二 |  | ローロ |
| ■ | FINAL STROKE WHEN CLOSING（RAM STROKE）（NOT displayed if function $F \Gamma_{-}=1$ ： <br> Lets you enable／disable the ram stroke on swing－leaves． <br> The ram stroke facilitates latching of the electric lock by activating the motors at maximum power during final closing． <br> ＝enabled（for 2 sec ） <br> Пロ＝disabled <br> －In case of systems with an absolute encoder，to enable this function a setup must be performed using the automatic leaf stop on the mechanical contact point． | ロII | ■1I |  | 『II |  | ロII |
| 1— | REVERSE STROKE WHEN OPENING displayed if function $F=1$ ）： <br> Lets you enable／disable the reverse stroke on leaf doors． <br> The reverse stroke facilitates unlatching of the electric lock．When the automatic system is closed，before starting to open，the motors give a brief push to close． <br> $=$ enabled（for 2 sec ） <br> 미＝disabled <br> （5）In case of systems with an absolute encoder，to enable this function a setup must be performed using the automatic leaf stop on the mechanical contact point． | ワ1I | ーII |  | 11E |  | ーII |
| I | ELECTRIC LOCK ON LEAF 2： <br> The board has a terminal dedicated to the connection of an electric lock． Normally the electric lock must be connected to leaf 1．If the electric lock is located on leaf 2，adjust the parameter．This parameter does not <br>  ப＝electric lock on leaf 2 <br> กロロ＝electric lock on leaf 1 | ロII | ロII |  | 11E |  | ロII |
| ［1］ | DELAY FOR OPENING LEAF（visualised only with the function ПП ＝ᄅ）： <br> You can set the delay time for starting leaf 2 opening with respect to leaf <br> 1，in order to avoid overlapping of the two leaves． <br> Adjustable from to 5 <br> Next the value 59，the viewing changes to minutes and tenths of a second （separated by a decimal point）and time is adjusted in 10 －second steps up to the maximum value of $l . \exists$ minutes． <br> e．g．：if the display shows $1 . \sqsupset$ ，the time is 1 min and 20 sec． | ローニ | 『1ロ |  | ロ1ニ |  | ロ1二 |
| 1 | LEAF 1 DECELERATION： <br> You can adjust the deceleration space as a percentage of the total travel of leaf 1. <br> Adjustable from to $\%$ ，in $1 \%$ steps． ＝no deceleration ＝minimum deceleration space ＝maximum deceleration space | 二\\|_ | 二｜I＿1 |  | 二10 |  | 二｜ll |


| Display | Advanced Function | cF |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 0 | 1 2 | 4 | $\exists \mathrm{E}$ | 5 |
| －2 | LEAF 2 DECELERATION（visualised only with the function $\bigcap_{\cap}$ П $=$ ）： You can adjust the deceleration space as a percentage of the total travel of leaf 2. <br> Adjustable from to $\%$ ，in $1 \%$ steps． <br> ［1］＝no deceleration <br> Ol＝minimum deceleration space <br> gI＝maximum deceleration space | 30 | 30 |  | 20 | 30 |
| PF | PRE－FLASHING： <br> You can enable／disable the pre－flashing．Pre－flashing duration $=3 \mathrm{sec}$ ． You can choose <br> 그＝disabled <br> ㅁ․＝pre－flashing before each movement <br> $\square L=$ pre－flashing before a closing movement <br> $\square P=$ pre－flashing before an opening movement <br> $\mathrm{PA}=$ pre－flashing only at the end of the pause time | no | no |  | no | no |
| Ph | closing photocells： <br> The intervention of closing photocells causes the reversing of automated system（opening） <br> 니＝operate the reversal only after the photocells are released <br> ワロ＝operate the reversal immediately | no | no |  | ח口 | no |
| Fld | ADMAP FUNCTION： <br> Allows operation in compliance with French regulation NFP 25／362． <br> ப＝enabled <br> $\cap \square=$ disabled | no | no |  | ח口 | no |
| EL | ANTI－CRUSHING SENSTIVITY： <br>  a stopif it the leaves are in the contact point search space（see the pa－ rameier The fouth co <br>  <br>  <br>  | $\square 1$ | 06 |  | 05 | 05 |
| 45 | ULTRA－SENSITIVITY： <br> This function activates an obstacle detection system，based on the control of the variation of the current absorbed by the motor，causing mmediate leaf reversal <br> $\begin{array}{ll}\unlhd & =\text { active } \\ \text { ח口 } & =\text { excluded }\end{array}$ | no | no |  | $Ч$ | $Ч$ |
| －日 | MECHANICAL STOP SEARCH ANGLE（NOT displayed if function <br>  will stop movement without reversing，if it encounters an obstacle or the will stop move <br> Adjustable from $\square$ to degrees <br> From $\square$ to 9 degrees，adjustments are made in 0.1 degree steps From to degrees，adjustments are made in 1 degree steps． | 11 | 11 |  | 4.0 | 4.10 |


| Display | Advanced Function | ■F |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | T1 | ■ | 1 | ב | ■ | ■ |
| Б, | SOFT TOUCH：（visualised only with the function $\left.E_{\square=}=\square \square \square\right):$ <br> After touching the travel stop point，the leaves reverse and then rest gently． <br> ＝active <br> ＝excluded This function can be useful to respect the impact curve specified by current standards． Other more detailed programming possibilities are feasible by PC programming（see dedicated instructions）． | ーII | ーロー |  | ーII |  | ローロ |
| E1 | OUT 1： <br> You can set the output OUT1（open collector N．O．）in one of the following functions： ＝always active $=$ FAIL－SAFE ＝INDICATOR LIGHT（off＝closed；on＝during opening and open／in pause；flashing＝during closing） <br> ＝COURTESY LIGHT（stays on for the duration of the movement （even in SETUP）in addition to the set time of function L ＝ACTIVE ERROR ＝automated system OPEN or in PAUSE ＝automated system CLOSED ＝automated system MOVING ＝automated system in EMERGENCY ＝automated system in OPENING ＝automated system in CLOSING <br> ＝electric lock control before OPENING and before CLOSING <br> ＝safety device ACTIVE <br> ＝TRAFFIC LIGHT function（active when OPENING and with automated system OPEN） <br> $14=$ timed output which can be activated from the second radio channel OMNIDEC（see function $\mathrm{L} \mid$ ） <br> 15 ＝output which can be activated from the second radio channel OMNIDEC（step－by－step function） <br> $=$ active during movement of leaf 1 <br> ＝active during movement of leaf 2 <br> ＝Instrusion detection <br> ＝System working on battery <br> If $\mathrm{L} \vdash$ is displayed，it indicates that the output is used as a TIMER set from the PC／MAC software． | [\|| | ［1II｜ |  | ［1｜］ |  | ｜＿l｜｜ |
| 1 | OUT 1 TIMING（visualised only with the function $\square \mid=\square \exists$ or $\square\|=\| 4$ ）： You can adjust the timing of OUT 1 output if a timed function has been selected with a time from 1 to minutes in 1－minute steps for functions 03－14 | 11 | 1－1 |  | 11 |  | ［1］ |
| ■1二 | OUT 2： <br> You can set the output OUT2（open collector N．O．）． See the options as al． | [1二 | 11ロ |  | [1二 |  | 『－1 |
| ロー | OUT 2 TIMING（visualised only with the function $\square 巳=$ $\square$ or $\square$ ＝ 14 ）： <br> Adjustable as $\mathrm{L} \mid$ ． | 11 | ［1］ |  | 11 |  | 1－1 |


| Display | Advanced Function | cF |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\square$ | 1 こ | 4 | $\exists$ | E | 5 |
| FG | MAINTENANCE REQUEST－CYCLE COUNTER（linked to the subse－ quent two functions）： <br> You can enable the signaling of maintenance request，or the cycle counter． <br> $\zeta=$ enable the SIGNALING when the program－ med number of cycles has been reached（as de－ fined in subsequent two functions $\cap \subset$ and $\cap d$ ）． <br> Signaling consists of a pre－flashing of 8 sec（in addition to the time may already be set with the function PF）before each movement． <br> no＝enable the CYCLE COUNTER，that will be displayed in the subse－ quent two functions nc and nd up to a displayed maximum of 65，530． <br> －형 If the number of cycles performed is greater than 65,530 the subsequent two functions $\mathrm{\square C}$ and nd will display 65 and 53，respectively． | $\bigcirc \square$ | กロ |  | $\square 1$ |  | $\bigcirc \square$ |
| ワレー | CYCLE PROGRAMMING（THOUSANDS）： <br> If $\mathrm{FS}=\mathrm{y}$ the display will show the number of thousands of cycles after which the signaling of maintenance request begins（can be set from $\square$ to 99）． <br> If FS ＝no the display will show the number of thousands of work cycles performed．The value displayed is updated with the succession of the cycles，interacting with the value in $\cap$ ． <br> 1 When $\mathrm{RS}=$ no you can reset the cycle counter：press simultaneously + and - for 5 sec ． | ㅁ） | ［1］ |  |  |  | ［1］ |
| ロロ | CYCLE PROGRAMMING（TENS）： <br> If $\mathrm{FS}=\bigsqcup$ the display will show the number of tens of cycles after which the signaling of maintenace request begins（can be set from to 9 ）． If $\mathrm{AS}=\mathrm{no}$ the display will show the number of tens of work cycles performed．The value displayed is updated with the succession of the cycles，interacting with the value in nc． <br> －${ }^{\text {Sin }}$ e．g．：if the system has performed 11,218 cycles， $\sqcap\llcorner=11$ and $\sqcap \square=21$ will be displayed | 미 |  |  | 01 |  | ［1］ |

## AUTOMATED SYSTEM STATUS：

You can exit programming，choosing whether or not to save the configuration you just performed．
1．set the choice：
$\zeta$ to SAVE and EXIT the programming
Пロ to EXIT the programming WITHOUT SAVING
2．press the button $\mathbf{F}$ to confirm；at the end the display returns to visualize the automated system status：

OO＝CLOSED
OI＝OPEN
$\square 己$＝Stationary then＂OPENS＂
03 ＝Stationary then＂CLOSES＂
OU＝In＂PAUSE＂
15＝Opening
OG＝Closing
$\square 7=$ FAIL SAFE in progress
OB＝checking BUS－2EASY devices in progress
09 ＝Pre－flash then＂OPENS＂
10 ＝Pre－flash then＂CLOSES＂
II＝Emergency open
12 ＝Emergency close
HP＝Hold position

## BUS－2EASY DEVICE INSTALLATION

You can add BUS－2EASY devices to the system at any time，proceeding as follows：
1．Cut off the electrical power to the board．
2．Install and set the BUS－2EASY accessories according to the instructions of the devices．
3．Connect the BUS－2EASY devices according to the instructions of Chapter ELECTRICAL CONNECTIONS．
4．Power up the board．
5．Complete the procedure for BUS－2EASY device entry．

## BUS－2EASY DEVICE ENTRY

1．Access BASIC programming and scroll through the functions up until bu．When $F$ is released，the display will show the BUS－2EASY de－ vices status（see the figure）．
2．Perform the entry：simultaneously press and hold $\boldsymbol{+}$ and $\boldsymbol{-}$ for at least 5 sec （during this time，the display will blink）．
3．$\unlhd$ will appear as a confirmation of entry completion．
4．Release the $\boldsymbol{+}$ and $\boldsymbol{-}$ buttons．The status of the BUS－2EASY devices will be displayed．
－5in If no BUS device has ever been entered in the board，the display will read IIー．
Opening photocells：


Fig．Visualising the BUS－2EASY status in the function bu：each segment of the display shows one type of device．

Fig. examples of BUS-2EASY status visualization on display.

In STAND BY (gate closed and in stand-by) with BUS-2EASY Encoder on leaf 1 and leaf 2 and BUS-2EASY Photocells correctly connected and entered.


In case of BUS-2EASY Encoder on leaf1 and leaf 2 and BUS-2EASY Photocells correctly connected and entered and with closing photocells engaged:


## CHECKING THE SECURING DEVICES ENTERED ON THE BOARD

To verify the types of BUS device recognised through the entry:

1. Press and hold the + button during stand-by visualisation; the segments corresponding to at least one entered device will go ON. E.g.:


To check the condition of the BUS-2EASY connection, verify the LED on the board:

## LED DL15 (Red)

| ON | Safety device engaged or pulse generator active |
| :--- | :--- |
| OFF | NO safety device engaged neither pulse generator active |

LED DL14 (Green)

| ON steady | Normal activity (led ON even if there are no devices). |
| :--- | :--- |
| Slow blinking (blink every <br> $\mathbf{2 , 5} \mathbf{~ s e c}$ ) | BUS-2EASY line short-circuit. | | }{$\mathbf{0 . 5} \mathbf{~ s e c}$ )} | Error in the BUS-2EASY connection. <br> Repeat the device entry. If the error occurs again, check: <br> - That there are no more than one device in the system with the same address. <br> - Calling error (number > or < the connected BUS devices). <br> - FAIL SAFE error on the BUS device. |
| :--- | :--- |
|  | Board in Sleep mode (if used). |

## TIME LEARNING - SETUP

When the board is powered, if a SETUP has never been performed, or if the board requests it, on the display indicates that a SETUP must be performed.

During SETUP, the connected BUS-2EASY accessories are always entered. The BUS-2EASY encoders entered by the SETUP must always be enabled using the parameterEn (BASIC Programming).
If a system without an encoder is installed, mechanical stops will be required for the leaves.
During SETUP all safety devices are disabled! Therefore, carry out the operation avoiding any transit in the leaf movement area.

Perform the SET-UP as follows:

1. Enter BASIC programming and go to the parameter $L L$, when $F$ is released -- will appear.
2. Ensure that the gate leaves are closed. Otherwise, proceed as follows:

- Press and hold -/R2 to close leaf 2
- Press and hold +/R1 to close leaf 1

His
Should pressing +/R1 and/or -/R2 command opening of the corresponding leaf, cut off power and, on terminal board J11 or J12, invert the cables of the corresponding motor.
3. With the gate leaves closed, launch SETUP by pressing and holding $\boldsymbol{\Psi}$ and $\boldsymbol{\sim}$ until $\zeta$ begins to flash on the display (about 3 sec).
4. Release $\boldsymbol{+} \boldsymbol{e}$. Leaf 1 begins its opening movement.

Operation WITHOUT Safecoder
Leaf 1 automatically acknowledges the mechanical stop.

## Operation WITH Safecoder or S800H ENC

Leaf 1 automatically acknowledges the mechanical stop. It will in any case be possible to stop leaf movement at any time and in the desired point by sending an OPEN A pulse.
5. On the display $\breve{c}^{2}$ will flash (only if 2 motors have been selected): leaf 2 begins opening.

## Operation WITHOUT Safecoder

Leaf 2 automatically acknowledges the mechanical stop.

## Operation WITH Safecoder or S800H ENC

Leaf 2 automatically acknowledges the mechanical stop. It will in any case be possible to stop leaf movement at any time and in the desired point by sending an OPEN A pulse.

## Steps 4 and 5 with function $F A$ :

$F A=\square 1$ (the limit switch determines the stopping of motion) the OPEN A pulse for stopping motion is ignored.
$F A=\square \beth$ (the limit switch determines the start of deceleration) with Safecoder installed or operator S800H ENC send an OPEN A pulse only after involving the opening limit switch, without Safecoder or with operators different than S800H ENC, make sure that the limit switch is engaged before the mechanical stop.
6. On the display $5 \exists$ will flash (only if 2 motors have been selected): leaf 2 begins closing.

## Operation WITHOUT Safecoder

Leaf 2 automatically acknowledges the mechanical stop.
7. On the display 54 flashes: leaf 1 begins closing.

## Steps 6 and 7 with function $F[$ :

F[ = = lil (the limit switch determines the stopping of motion) the OPEN A pulse for stopping motion is ignored.
F[ = ロこ (the limit switch determines the start of deceleration) with Safecoder installed or operator S800H ENC send an OPEN A pulse only after involving the closing limit switch, without Safecoder or with operators different than S800H ENC, make sure that the limit switch is engaged before the mechanical stop
8. 5 5lashes on the display: both leaves open at full speed.
9. 5F flashes on the display: both leaves close at full speed.
10. The board will automatically exit the programming menu and will display the automated system status ( dure has been completed correctly. If the procedure is not completed correctly, on the display will start flashing, indicating that a new SETUP procedure must be performed.

The deceleration spaces can be configured and modified from the display using the parameters $\ulcorner$ l and $\ulcorner\square$ (see Advanced Programming) without repeating the SETUP.

## TESTING THE AUTOMATED SYSTEM

Once installation and programming is completed, ensure that the system is operating correctly.
Be especially careful that the safety devices operate correctly and ensure that the system complies with all current safety regulations. Closeithe cover in the provided seat with gasket.

## Operation WITH Safecoder or S800H ENC

Leaf 2 automatically acknowledges the mechanical stop. It will in any case be possible to stop leaf movement at any time and in the desired point by sending an OPEN A pulse.

Leaf 1 automatically acknowledges the mechanical stop

## Operation WITHOUT Safecoder

- 

1


## FAAC

## MEMORISING THE RADIO CODE

The control board features an integrated 2-channel decoding system (DS, SLH/SLH LR, RC) called OMNIDEC. This system lets you memorise, using an additional receiver module (on J5 connector) and more radio controls having different technology but the same frequency. You can thus control both total opening (OPEN A) and partial opening (OPEN B).
The procedures indicated in this paragraph are only valid for the OMNIDEC system (receiver inserted on connector J13.) See the relative instructions for standard decoding boards (inserted on J14).

The different types of radio code (DS, SLH/SLH LR, LC/RC) can coexist simultaneously on the two channels. You can enter up to $\mathbf{2 5 0}$ radio codes divided between OPEN A and OPEN B/CLOSE.

To use different encoding systems on the same channel, you must complete the learning of each encoding system and then repeat the procedure for the other one.

Other, more detailed, programming options are available using a PC/MAC (see dedicated PC/MAC instructions). For example, you can set an automatic OPEN command on the radio channel to command an automatic cycle (open-pause-close) regardless of the selected logic.

## MEMORISING THE SLH/SLH LR RADIO CONTROLS

1. Press and hold + (OPEN A programming) or - (OPEN B/CLOSE programming).
2. After keeping the button pressed for about 5 sec, the corresponding radio LED (DL11 or DL12) will begin to flash slowly for about 20 sec.
3. Release the button.
4. Simultaneously press and hold P1 and P2 on the SLH/SLH LR radio control (only MASTER radio control).
5. The radio control LED will begin to flash.
6. Release both buttons.
7. Ensure that LED DL11 or DL12 on the board is still flashing (see point 2) and, while the radio control LED is still flashing, press and hold the desired button on the radio control (the radio control LED will go on steady).
8. The corresponding LED on the board (DL11 or DL12) will go on steady for 1 sec and then go off, indicating that memorisation has been completed.
9. Release the radio control button.
10. To complete memorisation, press the button of the memorised radio control twice in succession. The automated system will perform an opening cycle.

Ensure that there are no obstacles (by people or things) during the automated system movement.


## OPEN A



To enable other radio controls with the same system code, you must transfer the system code of the memorised radio control button to the button corresponding to the radio control you wish to add:

1. Simultaneously press and hold P1 and P2 on the memorised radio control.
2. The radio control LED will begin to flash.
3. Release both buttons.
4. Press and hold, while the radio control LED is still flashing, the memorised button (the radio control LED will go on steady).
5. Bring the radio controls close together, press and hold the corresponding button of the radio control you wish to add, and release only after the radio control LED flashes twice, indicating that memorisation has been completed.
6. Press the button of the memorised radio control twice in succession. The automated system will perform an opening cycle.

Ensure that there are no obstacles (by people or things) during the automated system movement.


## MEMORISING LC/RC RADIO CONTROLS (433MHz ONLY)

1. Press and hold + (OPEN A programming) or - (OPEN B/CLOSE programming).
2. After keeping the button pressed for about 5 sec, the corresponding radio LED (DL11 or DL12) will begin to flash slowly for about 20 sec.
3. Release the button.
4. During radio LED flashing, press the desired button of the LC/RC radio control.
5. The corresponding LED on the board (DL11 or DL12) will go on steady for 1 second, indicating that memorisation has been completed, and will begin flashing again for another 20 sec during which you can memorise another radio control.
6. When the 20 sec have elapsed, the LED will turn off, indicating that the procedure has been completed.
7. To add other radio controls, repeat the procedure from point

## REMOTE MEMORISATION OF LC/RC RADIO CONTROLS

With LC/RC radio controls you can remotely memorise other radio controls, i.e. without working directly on the board, using a previously memorised radio control.

1. Take a radio control that has already been memorised on one of the 2 channels (OPEN A or OPEN B/CLOSE) and move to the vicinity of the board.
2. Simultaneously press and hold P1 and P2 until both LEDs flash slowly for 5 sec.
3. Within 5 seconds, press the previously memorised radio control button to activate the learning phase for the selected channel.
4. The LED on the board corresponding to the channel in learning mode will flash for 20 sec within which another radio control code is transmitted by pressing the button.
5. The corresponding LED on the board will go on steady for 2 sec (indicating that memorisation has been completed) and will begin flashing again for another 20 sec , during which you can memorise other radio controls, and will finally go off.


## MEMORISING DS RADIO CONTROLS

1. On the DS radio control, choose the desired ON - OFF combination of the 12 dip-switches.
2. Press and hold + (OPEN A programming) or - (OPEN B/CLOSE programming).
3. After keeping the button pressed for about 5 sec , the corresponding radio LED (DL11 or DL12) will begin to flash slowly for about 20 sec .
4. Release the button.
5. During radio LED flashing, press the button of the radio control you wish to program.
6. The corresponding LED on the board (DL11 or DL12) will go on steady for 1 second and then go off, indicating that memorisation has been completed.
7. To add other different codes, repeat the procedure starting from point 1.
8. To add other radio controls with the same code, set the 12 dip-switches according to the same combination as the already memorised radio control.


## DELETING THE RADIO CONTROLS

This operation CANNOT be reversed. This will delete ALL the radio control codes memorised as both OPEN A and OPEN B/ CLOSE. The cancellation procedure is active only in gate status visualisation mode.

1. Press and hold

2. After pressing for about 5 sec , the DL12 LED begins to flash slowly; after another 5 sec of slow flashing and holding, the LEDs DL11 and DL12 begin flashing more rapidly (cancellation has started).
3. Once rapid flashing has stopped, LEDs DL11 and DL12 will go on steady, confirming the cancellation of all the radio codes (OPEN A and OPEN B/CLOSE) from the board memory.
4. Release - $\square$ . The LEDs will go off, indicating correct cancellation.

## SIGNALLING ERRORS AND ALARMS

In case of ERRORS（conditions that stop gate operation）or ALARMS（conditions that do not compromise gate operation）it is possible to see the number related to the warning．

These warnings will disappear in the following cycle only if the situation causing them is removed． When there is an ERROR，the ALARM LED will go on steady．When an ALARM is triggered，the ALARM LED starts to flash． By simultaneously pressing＋and－the display will show corresponding error number．

| $\mathrm{N}^{\circ}$ | ERROR | SOLUTION |
| :---: | :---: | :---: |
| $\square 1$ | Board broken | Replace the board |
| 口1］ | Thermal protection active | Wait for the board to cool down，check for overloads |
| ロコ | Motor 1 faulty | Check that the motor works and that the wiring is not interrupted or damaged |
| 04 | Motor 2 faulty |  |
| 05 | Invalid SETUP | Repeat board SETUP |
| 08 | BUS－2EASY device error | Ensure that no two pairs of devices have the same address． |
| 09 | BUS－2EASY output short－circuit | Check the connections of the connected and entered BUS－2EASY devices |
| 10 | Motor 1 limit switch error | Check the limit switch connections for motor 1 |
| 11 | Motor 2 limit switch error | Check the limit switch connections for motor 2 |
| 1 | BUS－2EASY call | Ensure that the BUS devices are operating correctly and，if necessary，repeat BUS device acquisition |
| $1 \exists$ | FAIL SAFE | Check that the safety devices（photocells）are operating correctly |
| 14 | Configuration error | Check that the board is configured correctly（basic and advanced programming）and，if necessary，repeat SETUP |
| 15 | Movement timeout reached | Check that the motors are blocked；check that any limit switches are activated correctly and that the mechanical stops are present． |
| 16 | Deep sleep | The board is in advanced energy－saving mode．No action required． |
| 17 | Motor 1 encoder fault | Check the connections or replace motor 1 encoder |
| 18 | Motor 2 encoder fault | Check the connections or replace motor 2 encoder |
| 19 | Incorrect memory data | Repeat BUS－2EASY device entry and／or re－program the board |
| 45 | Battery operation | No action required． |
| ロコ | High absorption at +24 V | Check that absorption by the accessories connected is within permitted limits |


| ${ }^{\circ}$ | ALARM |
| :---: | :---: |
| 20 | Obstacle on MOTOR 1 （only with en－ coder） |
| こり | Obstacle on MOTOR 2 （only with en－ coder） |
| อᄅ | MOTOR 1 current limited |
| こヨ | MOTOR 2 current limited |
| 25 | LOCK 1 output short－circuit |
| こG | LOCK 2 output short－circuit |
| こ7 | Nr ．of consecutive obstacles exceeded during opening |
| 28 | Nr．of consecutive obstacles exceeded during closing |
| $\exists 0^{0}$ | XF radio code memory full |
| $\exists 1$ | Tampering alarm |
| ヨコ | Emergency active |
| $\exists 5$ | TIMER active and TIMER function operating： |
| 40 | Service request |
| 50 | The HOLD POSITION is operating（active on PC／MAC ） |
| 60 | TIMER active and error in TIMER data |
| ロコ | Loss of time and date on the board（only if the TIMER is operating） |
| ロコ | JOLLY TIMER is activated |
| 54 | TIMER DISABLED is operating |

Solution／Description
Remove any possible obstacle on leaf 1

Remove any possible obstacle on leaf 2
Check the force set on motor 1
Check the force set on motor 2
Remove the cause of the short－circuit
Remove the cause of the short－circuit
Remove any possible obstacle．
Should the problem persist，repeat SETUP
Remove any possible obstacle．
Should the problem persist，repeat SETUP
Cancel the radio codes that are not being used using the PC program or use an additional DEC／MINIDEC／ RP module

Movement was performed with automation in status St＝ill or 이．Perform a manoeuvre cycle．
Check that the emergency input is not active（configuration only possible from $\mathrm{PC} / \mathrm{Mac}$ ）
TIMER function is operating
Contact the installer for maintenance
HOLD POSITION function is operating
Reload a correct TIMER configuration with the PC／MAC programme
Reload the time and date with the PC／MAC programme and replace the BAT1－CR2032 buffer battery
JOLLY TIMER is enabled by terminal board J3
TIMER is disabled by terminal board J3

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