

ISTRUZIONI PER L’USO - NORME DI INSTALLAZIONE USE AND INSTALLATION INSTRUCTIONS

INSTRUCTIONS POUR L'EMPLOI - NORMES D'INSTALLATION INSTRUCCIONES PARA EL USO - NORMAS DE INSTALACIÓN BETRIEBSANLEITUNG - INSTALLATIONSVORSCHRIFTEN

# $\square \square \square \square$ 

## AVVERTENZE PERL'INSTALLATORE

## OBBLIGHI GENERALI PER LA SICUREZZA

1) ATTENZIONE! È importante per la sicurezza delle persone seguire attentamente tutta l'istruzione. Una errata installazione o un errato uso del prodotto può portare a gravi danni alle persone.
2) Leggere attentamentele istruzioni prima di iniziarel'installazione del prodołto.
3) Imateriali dell'imballaggio (plastica, polistirolo, ecc.) non devono essere lasciati alla portata dei bambini in quanto potenziali fonti di pericolo.
4) Conservarele istruzioni per riferimenti futuri.
5) Questo prodotto è stato progettato e costruito esclusivamente per I'utilizzo indicato in questa documentazione. Qualsiasi altro utilizzo non espressamente indicato potrebbe pregiudicarel'integrità del prodotto e/o rappresentare fonte di pericolo.
6) GENIUS declina qualsiasi responsabilità derivata dall'uso improprio o diverso daquello percuil'automatismo è destinato.
7) Noninstallarel'apparecchio in atmosferaesplosiva: la presenza di gas ofumi infiammabili costituisce un grave pericolo per la sicurezza.
8) Gli elementi costruttivi meccanici devono essere in accordo con quanto stabilito dalle Norme EN 12604 e EN 12605.
Per iPaesi extra-CEE, oltre ai riferimenti normativi nazionali, per ottenere un livello di sicurezza adeguato, devono essere seguitele Norme sopra riportate.
9) GENIUS nonè responsabile dell'inosservanza della Buona Tecnica nella costruzione delle chiusure da motorizzare, nonché delle deformazioni che dovessero intervenire nell'utilizzo.
10) L'installazione deve essere effettuata nell'osservanza delle Norme EN 12453 e EN 12445 . Il livello di sicurezza dell'automazione deve essere C+E.
11) Prima di effettuare qualsiasi intervento sull'impianto, toglierel'alimentazione elettrica.
12) Prevedere sulla rete di alimentazione dell'automazione un interruttore onnipolare con distanza d'apertura dei contatti uguale o superiore a 3 mm . È consigliabilel'uso di un magnetotermico da6A coninterruzione onnipolare.
13) Verificare che a monte dell'impianto visia un interruttore differenziale con sogliada0,03 A.
14) Verificare che I'impianto di terra sia realizzato a regola d'arte e collegarvi le partimetalliche della chiusura.
15) L'automazione dispone di una sicurezza intrinseca antischiacciamento costituita daun controllo di coppia. E' comunque necessario verificarne la sogli di intervento secondo quanto previsto dalle Norme indicate al punto 10.
16) Idispositivi di sicurezza (norma EN 12978) permettono di proteggere eventuali aree di pericolo da Rischi meccanici di movimento, come ad Es. schiacciamento, convogliamento, cesoiamento.
17) Perogni impianto è consigliato I'utilizzo di almeno una segnalazione luminosanonché di un cartello di segnalazione fissato adeguatamente sulla strutturadell'infisso, oltre ai dispositivi citati al punto " 16 ".
18) GENIUS declina ogniresponsabilità ai fini della sicurezzae del buon funzionamento dell'automazione, in caso vengano utilizzati componenti dell' impianto non di produzione GENIUS.
19) Perla manutenzione utilizzare esclusivamente parti originali GENIUS.
20) Non eseguire alcuna modifica sui componenti facenti parte del sistema d'automazione.
21) L'installatore deve fornire tutte le informazioni relative al funzionamento manuale del sistema in caso di emergenza e consegnare all'Utente utilizzatore dell'impianto il libretto d'avvertenze allegato al prodotto.
22) Non permettere ai bambinio persone di sostare nelle vicinanze del prodotto durante il funzionamento.
23) Tenere fuori dalla portata dei bambini radiocomandio qualsiasi altro datore di impulso, per evitare chel'automazione possa essere azionata involontariamente.
24) Il transito trale ante deve avvenire solo a cancello completamente aperto.
25) L'Utente utilizzatore deve astenersi da qualsiasi tentativo di riparazione o d'intervento diretto e rivolgersi solo a personale qualificato.
26) Tutto quello che non è previsto espressamente in queste istruzioni non è permesso

## IMPORTANT NOTICE FOR THE INSTALLER

## GENERAL SAFETY REGULATIONS

1) ATTENTION! To ensure the safety of people, it is important that you read all the following instructions. Incorrect installation or incorrect use of the product could cause serious harm to people.
2) Carefully read the instructions before beginning to install the product.
3) Do not leave packing materials (plastic, polystyrene, etc.) within reach of children as such materials are potential sources of danger.
4) Store these instructions for future reference.
5) This product was designed and built strictly for the use indicated in this documentation. Any other use, not expressly indicated here, could compromise the good condition/operation of the product and/or be a source of danger.
6) GENIUS declines all liability caused by improper use or use other than that for which the automated system was intended.
7) Do not install the equipment in an explosive atmosphere: the presence of inflammable gas or fumes is a serious danger to safety.
8) The mechanical parts must conform to the provisions of Standards EN 12604 and EN 12605.
For non-EU countries, to obtain an adequate level of safety, the Standards mentioned above mustbe observed, in addition to national legal regulations.
9) GENIUS is not responsible for failure to observe Good Technique in the construction of the closing elements to be motorised, or for any deformation that may occur during use.
10) The installation must conform to Standards EN 12453 and EN 12445 . The safety level of the automated system must be C+E.
11) Before attempting any job on the system, cutoutelectrical power.
12) The mains power supply of the automated system must be fitted with an allpole switch with contact opening distance of 3mm or greater. Use of a 6 A thermal breaker with all-pole circuit break is recommended.
13) Make sure that a differential switch with threshold of 0.03 A is fitted upstream of the system.
14) Make sure that the earthing system is perfectly constructed, and connect metal parts of the means of the closure to it.
15) The automated system is supplied with an intrinsic anti-crushing safety device consisting of a torque control. Nevertheless, its tripping threshold must be checked as specified in the Standards indicated at point 10.
16) The safety devices (EN 12978 standard) protect any danger areas against mechanical movement Risks, such as crushing, dragging, and shearing.
17) Use of atleast one indicator-light is recommended for every system, as well as a warning sign adequately secured to the frame structure, in addition to the devices mentioned at point " 16 ".
18) GENIUS declines all liability as concerns safety and efficient operation of the automated system, if system components not produced by GENIUS are used.
19) For maintenance, strictly use original parts by GENIUS.
20) Do not in any way modify the components of the automated system.
21) The installer shall supply all information concerning manual operation of the system in case of an emergency, and shall hand over to the user the warnings handbooksupplied with the product.
22) Do not allow children or adults to stay near the product while it is operating.
23) Keep remote controls or other pulse generators away from children, to prevent the automated system from being activated involuntarily.
24) Transit through the leaves is allowed only when the gate is fully open.
25) The user must not attempt any kind of repair or direct action whatever and contact qualified personnel only.
26) Anything not expressly specified in these instructions is not permitted.

## CONSIGNES POUR L'INSTALLATEUR <br> RÈGLES DE SÉCURITÉ

1) ATTENTION! Il est important, pour la sécurité des personnes, de suivre à la lettre toutes les instructions. Une installation erronée ou un usage erroné du produit peut entraîner de graves conséquences pour les personnes.
2) Lire attentivementles instructions avant d'installer le produit.
3) Lesmatériaux d'emballage (matière plastique, polystyrène, etc.) ne doivent pas être laissés à la portée des enfants car ils constituent des sources potentielles de danger.
4) Conserver les instructions pour les références futures.
5) Ceproduitaété conçuetconstruitexclusivement pourl l'usage indiqué dans cette documentation. Toute autre utilisation non expressément indiquée pourrait compromettrel'intégrité du produitet/ou représenterune source de danger.
6) GENIUS décline toute responsabilité qui dériverait d'usage impropre ou différent de celui auquel l'automatisme est destiné.
7) Ne pas installer l'appareil dans une atmosphère explosive: la présence de gaz ou de fumées inflammables constitue un grave dangerpour la sécurité.
8) Lescomposants mécaniques doiventrépondre aux prescriptions des Normes EN 12604 et EN 12605.
Pour les Pays extra-CEE, I'obtention d'un niveau de sécurité approprié exige non seulementle respect des normes nationales, maiségalementle respect $\dagger$ desNormessusmentionnées.
9) GENIUSn'estpas responsable du non-respect de la BonneTechnique dansla construction des fermetures à motoriser, ni des déformations qui pourraient intervenir lors de l'utilisation.
10) L'installation doitêtre effectuée conformément aux Normes EN 12453 et EN 12445. Le niveau de sécurité de l'automatisme doitêtre $C+E$.
11) Couperl'alimentationélectrique avanttoute intervention sur l'installation.
12) Prévoir, sur le secteur d'alimentation de l'automatisme, un interrupteur omnipolaire avecune distance d'ouverture des contactségale ou supérieure à 3 mm . On recommande d'utiliser un magnétothermique de 6A avec interruption omnipolaire.
13) Vérifier qu'il y ait, en amont de l'installation, un interrupteur différentiel avec un seuil de 0,03 A.
14) Vérifier que la mise à terre est réalisée selon les règles de l'artety connecter les pièces métalliques de la fermeture.
15) L'automatisme dispose d'une sécurité intrinsèque anti-écrasement, formée d'un contrôle du couple. Il est toutefois nécessaire d'en vérifier le seuil d'intervention suivantles prescriptions des Normes indiquées au point 10.
16) Les dispositifs de sécurité (norme EN 12978) permettent de protéger des zones éventuellement dangereuses contre les Risques mécaniques du mouvement, commel'écrasement, l'acheminement, le cisaillement.

## CONTROL BOARD JA592

## 1. WARNINGS

Important: Before attempting any work on the control board (connections, maintenance), always turn off power.

- Install, upstream of the system, a differential thermal breaker (Residual Current Device) with adequate tripping threshold.
- Connect the earth cable to the appropriate terminal on the J3 connector of the equipment (see fig.2).
- Always separate power cables from control and safety cables (push-button, receiver, photocells, etc.). To avoid any electric noise, use separate sheaths or a shielded cable (with earthed shield).


## 2. TECHNICAL SPECIFICATIONS

| Powersupply | $230 \mathrm{~V} \sim(+6 \%-10 \%)-50 \mathrm{~Hz}$ |
| :--- | ---: |
| Absorbedpower | 10 W |
| Motormax.load | 800 W |
| Accessoriesmax.load | $0,5 \mathrm{~A}$ |
| Electriclockmax.load | 15 VA |
| Operatingambientemperature | $-20^{\circ} \mathrm{C}+55^{\circ} \mathrm{C}$ |
| Protectionfuses | $2($ see fig. 1) |

## 3. LAYOUT AND COMPONENTS



| LedOP_A | TOTALLYOPENLED |
| :---: | :---: |
| Led OP_B | LED: OPEN LEAF 1 / CLOSE |
| Led STOP | LED STOP |
| Led FSWCL | LED: CLOSING SAFETY DEVICES |
| Led FSWOP | LED: OPENING SAFETY DEVICES |
| LedFCAI | LED:LEAF I OPENING LIMIT-SWITCH |
| LedFCCl | LED: LEAF I CLOSING LIMIT-SWITCH |
| LedFCA2 | LED: LEAF2OPENINGLIMIT-SWITCH |
| LedFCC2 | LED:LEAF2CLOSING LIMIT-SWITCH |
| DLIO | LED:TIMELEARNINGSIGNALLING |
| J1 | LOWVOLTAGETERMINALBOARD |
| J2 | RAPID CONNECTOR 5 PINS |
| J3 | 230 VAC POWER SUPPLY TERMINAL BOARD |
| J4 | MOTORS AND FLASHING LAMP CONNECTION TERMINAL BOARD |
| J5 | INDICATOR-LIGHT AND ELECTRIC LOCK TERMINAL BOARD |
| J6 | LIMIT-SWITCH AND ENCODER TERMINAL BOARD |
| F1 | MOTORS AND TRANSFORMER PRIMARY WINDING FUSE (F 5A) |
| F2 | LOW VOLTAGE AND ACCESSORIES FUSE (T 800mA) |
| F | TIME LEARNING SELECTION PUSH-BUTTON |
| DS1 | 1ST GROUP OF MICROSWITCH PROGRAMMING |
| DS2 | 2ND GROUP OF MICROSWIICH PROGRAMMING |

4. ELECTRIC CONNECTIONS


### 4.1. Connection of photocells and safety devices

Before connecting the photocells (or other devices) we advise you to select the type of operation according to the movement area they have to protect (see fig.3):
Opening safety devices: they operate only during the gate opening movement and, therefore, they are suitable for protecting the area between the opening leaves and fixed obstacles (walls, etc) against the risk of impact and crushing.
Closing safety devices: they operate only during the gate closing movement and, therefore, they are suitable for protecting the closing area against the risk of impact.


Opening/closing safety devices: they operate during the gate opening and closing movements and, therefore, they are suitable for the opening and closing areas against the risk of impact.

It is recommends use of the lay-out in fig. 4 (in the event of fixed obstacles at opening) or in fig. 5 (no fixed obstacles).
N.B. If two or more devices have the same function (opening or closing), they should be connected to each other in series (see fig. 12). N.C. contacts must be used.



Fig. 10


Fig. 11


Fig. 12

Connection of 2 N.O. contacts in parallel (e.g. Open A, Open B)


Fig. 13
4.2. Terminal board J3-Power supply (fig. 2)

PE: Earth connection
N: 230 V ~ power supply (Neutral)
L : 230 V~ power supply (Line)
NB.:Forcorrectoperation, the board mustbe connected to the earth conductor in the system. Install an adequate differential thermal breaker (RCD) upstream of the system.
4.3. Terminal board J 4 - Motors and flashing lamp (fig. 2)

M1 : Terminals $1 / 2 / 3=$ COM/OP/CL: Connection to Motor 1 Can be used in the single-leaf application
M2 : Terminals $4 / 5 / 6=$ COM/OP/CL: Connection to Motor2 Cannot be used in the single-leaf application
LAMP : Terminals $7 / 8=$ Flashing lamp output ( $230 \mathrm{~V} \sim$ )
4.4. Terminal board J1-Accessories (fig. 2)

OPEN A - Terminal 9 plus a negative = "Total Opening" command (N.O.): any pulse generator (push-button, detector, etc.) which, by closing a contact, commands opening and/or closing of both gate leaves.
To install several full opening pulse generators, connect the N.O. contacts in parallel (see fig.13).
OPEN B - Terminal 10 plus a negative $=$ "Partial Opening" command (N.O.) / Closing: any pulse generator (pushbutton, detector, etc.) which, by closing a contact, commands opening and/or closing of the leaf driven by motor M1. In the $\mathbf{B}$ and $\mathbf{C}$ logics, it always commands closing of both leaves.
To install several partial opening pulse generators, connect the N.O. contacts in parallel (see fig.13).
STP - Terminal 11 plus a negative $=$ STOP contact (N.C.): any device (e.g. a push-button) which, by opening a contact, is able to stop gate movement.
To install several STOP devices, connect the N.C. contacts in series (see fig.12).
NB.:IfSTOPdevices are not connected, jumperconnect the STP terminals and - common.
CLFSW - Terminal 12 plus a negative $=$ Closing safety devices contact (N.C.): The purpose of the closing safety devices are to protect the leaf movement area during closing. During closing, in the A-SP-E-EP logics, the safety devices reverse the movement of the gate leaves, or stop and reverse the movement when they are released (see programming of microswitch DS2-SW2). During the closing cycle in logics B and $\mathbf{C}$, they interrupt movement. They never operate during the opening cycle. If the closing safety devices operate when the gate is open, they preventthe leaf closing movement.
NB.: If no closing safety devices are connected, jumper connect terminals CL and -TX FSW (fig. 7).

OPFSW - Terminal 13 plus a negative $=$ Opening safety devices contact (N.C.): The purpose of the opening safety devices are to protect the leaf movement area during opening. During opening, in the A-SP-E-EPlogics, the safety devices stop the movement of the gate leaves and reverse the movement when they are released. During the opening cycle in logics B and C, they interrupt movement. They never operate during the closing cycle.
Ifthe openingsafety devices operatewhenthegateisclosed, theypreventtheleafopeningmovement.
NB.: If no opening safety devices are connected, jumper connect inputs OP and -TX FSW (fig. 7).

-     - Terminal 14/15/16 = Negative for power supply to accessories, are all negative.
+     - Terminal 17/18=24 Vdc - Positive for power supply to accessories, are all positive.
Important: Accessories max. load is 500 mA . To calculate absorption values, refer to the instructions for individual accessories.
-TXFSW - Terminal 19 = Negative for powersupply to photocell transmitters.
If you use this terminal for connecting the negative for supplying power to the photocell transmitters, you may, if necessary, also use the FAIL SAFE function (see programming of microswitch DS2-SW3).
If this function is enabled, the equipment checks operation of the photocells before every opening or closing cycle.
4.5. TerminalboardJ5-Indicator-lightandElectriclock (fig.2)
W.L. - Terminal $20=$ Power supply to indicator-light Connecta24Vdc-3W max. indicator-light, ifrequired, between this terminal and the +24 V supply. To avoid compromising correct operation of the system, do not exceed the indicated power.
LOCK - Terminal 21 = Power supply to electric lock If required/necessary, connect a 12 V ac electric lock between terminal 21 and the terminal 18 the +24 V supply.


### 4.6. Connector J2 - Rapid connector 5 pins

This is used for rapid connection. Connect the accessory, with the components side facing the inside of the card. Insert and remove only afterswitching off power.

4.7. Terminal board J6 - Limit-switches and/or encoder(fig.2)

These inputs are designed forconnection ofopening and closing limit-switches which, according to type of programming - can commandeitherleafstop orstart of deceleration. Unconnected limit-switchesmustbejumperconnected (ifnone are connected, this is not necessary).
Encoders can also be used to detect the leaf's angular position and to thus obtain deceleration and stop positions independent of work time.
Limit-switches and encoders can also be used in combinationto stop movement before the mechanical stop limit is reached. To wire, see fig. 17a, 17b and 17c.
FCA1 - Leaf 1 opening limit-switch
FCCl - Leaf 1 closing limit-switch
FCA2 - Leaf 2 opening limit-switch
FCC2 - Leaf 2 closing limit-switch

N.B.: Maximum configurations are shown on the drawings. All intermediate configurations are allowed, using only some elements (only 1 encoder, only 1 limit-switch, 2 encoders and 2 limit-switches etc.).
5. MICROSWITCH PROGRAMMING

Fig. 18


DS1




5. MICRO

The equipment is endowed with two groups of microswitches DS1 (fig. 18) and DS2 (fig. 19) - which make it possible to program the gate operation parameters.

### 5.1. MICROSWITCHES DSI (fig. 18)

## Leaf 1 and 2 force

By using microswitches SW1, SW2 and SW3, the force (and thus anti-crushing safety) of the operator connected to leaf 1 can be programmed. The same operation has to be repeated on the motor connected to leaf 2, by using microswitchesSW4, SW5 and SW6.

## Function logic

The automated system's function logic can be selected with microswitchesSW7, SW8, SW9 andSW10. Byselecting an automatic logic (A,SP), the combination of microswitches enables selection of pause time too (waiting time, in opening position, before automatic re-closing).
The available logics - their operation is described in tables 3/a-b-c-d-e-f, are as follows: A - SP (Automatic), E - EP - B (Semiautomatic), C (Dead-man).

## Closing leaf delay

Programming of microswitches SW 11 andSW12 enables delay of the closing start of leaf 1 with respect to leaf 2, in order to avoid the leaves overlapping during movement, and thus increase the safety of the system.

### 5.2. MICROSWITCHES DS2 (fig. 19)

## Opening leaf delay

Programming of microswitch SW1 enables delay of the opening start of leaf 2 with respect to leaf 1 , in order to avoid the leaves obstructing each other during the initial stage of movement.

## Closing photocells logic

By using microswitch SW2, you can select the type of behaviour of the automated system if the photocells protecting the gate closingmovementare engaged. You can obtain either immediate reversing of the leaves or a stop followed by reversing when the photocells are disengaged.

## Fail safe

Programming the microswitch SW3 makes it possible to activate orde-activate the photocells control test. When Fail safe is active, the equipment checks the photocells before every opening or closing movement.

## Reversing stroke + over-pushing stroke

By using the microswitch SW4, you can activate the "reversing stroke" and the "over-pushing stroke". The "reversing stroke"pushes the leaves to close for a few moments before opening the gate, thus facilitating release of the electric lock. The "over-pushing stroke" commands a closing thrust at full force when the gate has already reached its stop limit, thus facilitating the locking of the electriclock.

## 6. START-UP

6.1. LEDCHECK

The table below shows the status of the LEDs in relation to to the status of the inputs.
Note the following: Led LIGHTED = closed contact
Led off = open contact
Check the state of the LEDs as per Table.
Operation of the status signalling LEDs

| LEDs | LIGHTED | OFF |
| :--- | :--- | :--- |
| OP_A | Command activated | Comando inattivo |
| OP_B | Command activated | Comando inattivo |
| STOP | Command inactive | Command activated |
| FSWCL | Safety devices disengaged | Safety devices engaged |
| FSWOP | Safety devices disengaged | Safety devices engaged |
| FCA1 (if used) | Limit-switch free | Limit-switch engaged |
| FCC1 (if used) | Limit-switch free | Limit-switch engaged |
| FCC2 (if used) | Limit-switch free | Limit-switch engaged |
| FCA2 (if used) | Limit-switch free | Limit-switch engaged |

NB.: The status of the LEDs while the gate is at rest are shown in bold.
Furthermore, the DL10 LED is on the board and functions as detailed in the following table:

| DL10 |  |  |
| :---: | :---: | :---: |
| Gate closed atrest: <br> OFF | Gate movingoron <br> pause: <br> like indicator-light | Timelearning: <br> flashesrapidly |

### 6.2. ROTATION DIRECTION AND FORCE CHECK

1) Program the functions of the control board according to need, as shown in Chapter 5.
2) Cut power to the electronic control equipment.
3) Release the operators and manually move the gate to the mid-point of the opening angle.
4) Re-lock the operators.
5) Restore power.
6) Send and opening command on the OPEN A input (fig.2) and check if the gate leaves are being commanded to open.
N.B.: If the first OPEN A pulse commands a closing, cut power and change over the phases of the electric motor (brown and black wires) on the terminal board.
7) Check power setting of the motors and, if necessary, modify it (see Chapter 5.1).
N.B.: If using hydraulic operators, force should be programmed to maximum level (8)
8) Stop leaf movement with a STOP command.
9) Release the operators, close the leaves and re-lock the operators.

### 6.3. LEARNING OF OPERATING TIMES

WARNING: during the learning procedure, the safety devices are disabled! Therefore any transit must be avoided in the leaf movement area when this operation is carried out.

Opening/closing time is established by a learning procedure which varies slightly according to whether you are using limitswitches.

### 6.3.1. LEARNING OF NORMAL TIMES

## - SIMPLE LEARNING:

Check if the leaves are closed, and then press F push-button for one second: DL10 LED begins flashing and the leaves begin the opening movement.
Wait for the leaf to reach the opening stop limit and then supply an OPEN A pulse (with the radio control or with the key controlled push-button) to stop the movement: the leaves stop and the DL10 LED stops flashing.
The procedure has ended and the gate is ready to operate. Next pulse closes leaves and they stop on automaticaly reaching closed position.

## - ADVANCED COMPLETE LEARNING:

Check if the leaves are closed, and then press F push-button for more than 3 seconds: DL10 LED begins flashing and the leaf 1 begins the opening movement. The following functions can be commanded by the OPEN A pulses (by radio control or key controlled push-button):
$1^{\circ}$ OPEN - Deceleration at opening of leaf 1
$2^{\circ}$ OPEN - Leaf 1 stops at opening and leaf 2 begins its opening movement
$3^{\circ}$ OPEN - Deceleration at opening of leaf 2
$4^{\circ}$ OPEN - Leaf 2 stops at opening and immediately begins its closing movement
$5^{\circ}$ OPEN - Deceleration at closing of leaf 2
$6^{\circ}$ OPEN - Leaf 2 stops at closing and leaf 1 begins its closing movement
$7^{\circ}$ OPEN - Deceleration at closing of leaf 1
$8^{\circ}$ OPEN - Leaf 1 stops at closing
The DL10 LED stops flashing and the gate is ready for normal operation.
Notes: - If you wish to eliminate deceleration in certain stages, wait for the leaf to reach its stop-limit and supply 2 consecutive Open pulses (by 1 second).
-If only one leaf is present, the entire sequence must nevertheless be effected. When the leaf has finished opening, supply 5 Open pulses until the leaf begins to close, and then resume normal operation.
-It wind effected areas it is best to allow 2 second after the leaf reaches open stop befor supplying Open A to ensure full closing.

- Limitswitchesorencodermustbe usedin condominium applications in orderto guarantee the repeatability of the slow-down. Otherwise the leaf could notreach the limitstop with slow-down.
- If, during closing / opening, the cycle stops for more consecutive times, the leaf could not reach the limit stop with slow-down. Atthe first complete cycle without interruptions, the system recognizes the limitstops and carries out again the programmed slow-downs.


### 6.3.2. LEARNING WITH LIMIT-SWITCHES

Learning with limit-switches can be done in two different ways:

## - SIMPLE LEARNING:

Check if the leaves are closed, and then press $F$ push-button for 1 second: DL10 LED begins flashing and the leaves begin the opening movement.
The motors stop automatically when the opening limit-switches are reached, but an OPEN A pulse must be given (by radio control or key push-button) to end the cycle; the leaves stop and the DL10 LED stops flashing.
The procedure has ended and the gate is ready to operate. Next pulse closes leaves and they stop on automaticaly reaching closed position.

## - ADVANCED COMPLETE LEARNING:

Check if the leaves are closed, and then press the F push-button for more than 3 seconds: DL10 LED begins flashing and leaf 1 begins the opening movement. The leaves automatically decelerate when they reach the limit-switches, and therefore, it is sufficient to inform the equipment that the stop limits have been reached by means of OPEN A pulses (by radio control orkey pushbutton):

FCA1 - Deceleration at opening of leaf 1
$1^{\circ}$ OPEN - Leaf 1 stops at opening and leaf 2 begins its opening movement
FCA2 - Deceleration at opening of leaf 2
$2^{\circ}$ OPEN - Leaf 2 stops at opening and immediately begins its closing movement
FCC2 - Deceleration at closing of leaf 2
$3^{\circ}$ OPEN - Leaf 2 stops at closing and leaf 1 begins its closing movement
FCC1 - Deceleration at closing of leaf 1
$4^{\circ}$ OPEN - Leaf 1 stops at closing
the DL10 LED stops flashing and the gate is ready for normal operation
Notes: •If you wish to eliminate deceleration in some stages, you mustsupply an Open pulse within 1 second of reaching the limit-switch.

- If some limit-switches are not installed, start the corresponding deceleration by supplying an Open pulse (which replaces the limit-switch).
- If only one leaf is present, the entire sequence must nevertheless be effected. When the leaf has finished opening, supply 5 Open pulses until the leaf begins to close, and then resume normal operation.
- It wind effected areas it is best to allow 2 second after the leafreaches open stop beforsupplying Open A to ensure full closing.


### 6.3.3. LEARNING TIMES WITH ENCODER

Learning with the encoder can be done in two different ways:

## - SIMPLE LEARNING:

Check if the leaves are closed, and then press F push-button for 1 second: DL10 LED begins flashing and the leaves begin the opening movement.
The movement stops automatically when the opening stop limit is reached and the DL10 LED stops flashing.
The procedure has ended and the gate is ready to operate, using fixed deceleration.
ENGLISH

| LOGIC"E" | PULSES |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GATESTATUS | OPEN-A | OPEN-B | STOP | OPENINGSAFETYDEVICES | CLOSINGSAFETYDEVICES | OP/CLOS.SAFETY DEVICE | W.L. |
| CLOSED | Opens the leaves | Opens the free leaf | No effect (OPEN disabled) |  | No effect | No effect (OPEN disablea) | OFF |
| OPEN | Re-closes the leaves immediately | Re-closes the leaf immediately | Stops operation | No effect | No effect (OPEN disabled) |  | lighted |
| ATCLOSING | Re-opens the leaves inmediately | Re-opens the leaf immeditaly (1) |  | No effect (saves OPEN) | see paragraph 5.2. | Locks and, on release, reverses at opening | flasting |
| ATOPENING | Stops operation |  |  | Reverses of closing | No effect | Locks and, on release, continues opening | lighted |
| LOCKED | Closes the leafleaves(with CLOSING SAFEN DEVVCES active, opens at 2nd puses) |  | No effect (OPEN disabled) | No effect | No effect (OPEN disabled) |  | lighted |


| LOGIC "EP" | PULSES |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GATE STATUS | OPEN-A | OPEN-B | STOP | OPENING SAFETY DEVICES | CLOSING SAFETY DEVICES | OP/CLOS. SAFETY DEVICE | W.L. |
| CLOSED | Openstheleaves | Opensthefreeleaf |  | OPENdisabled) | Noeffect | Noeffect(OPENdisabled) | OFF |
| OPEN | Re-closestheleaf/leavesimmediately |  | Stopsoperation | Noeffect(OPENdisabled) | Noeff | isabled) | lighted |
| AT CLOSING | Stopsoperation |  |  | Noeffect(savesOPEN) | seeparagraph 5.2. | Locksand, onrelease, reverses atopening | flasking |
| ATOPENING | Stopsoperation |  |  | Reveres atclosing | Noeffect | Locksand, onrelease, continues opering | lighted |
| LOCKED | Restartsmovingin reversedirection (alwaysclosesafteraStop) |  | Noeffect(OPENdisabled) | Noeffect(ffitmustopen,itdisablesOPEN) | Noeffect (fftmustclose, Itdisables OPEN) | Noeffect(OPENdisabled) | lighted |


| LOGIC "B" | PULSES |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GATE STATUS | OPEN-A | OPEN-B | STOP | OPENING SAFETY DEVICES | CLOSING SAFETY DEVICES | OP/CLOS. SAFETY DEVICE | W.L. |
| CLOSED | Openstheleaforleaves | Noeffect | Noeffect (OPEN-Adisabled) | Noeffect (OPEN-Adisabled) | Noeffect (OPEN-Bdisabled) | Noeffect (OPEN-Adisabled) | OFF |
| OPEN | Noeffect | Closestheleavesorleaf | Noeffect (OPEN-Bdisabled) |  | Noeffect (OPEN-Bdisabled) | Noeffect (OPEN-Bdisabled) | lighted |
| AT CLOSING | Reveres atopening | Noeffect | Stopsoperation | Noeffect | Stopsoperation (OPEN-Bdisabled) | Stopsoperation (OPEN-A/Bdisabled) | flashing |
| ATOPENING | Noeffect | Noeffect |  | Noeffect (OPEN-Adisabled) | Noeffect | Stopsoperation (OPEN-A/Bdisabled) | lighted |
| LOCKED | Openstheleaforleaves | Closestheleavesorleaf | Noeffect (OPEN-A/Bdisabled) | Noeffect (OPEN-Adisabled) | Noeffect(OPEN-Bdisabled) | Noeffect (OPEN-A/Bdisabled) | lighted |
| Table 3/f |  |  |  |  |  |  |  |
| LOGIC "C" | COMMANDS ALWAYS PRESSED |  | PULSES |  |  |  |  |
| GATE STATUS | OPEN-A | OPEN-B | STOP | OPENING SAFETY DEVICES | CLOSING SAFETY DEVICES | OP/CLOS. SAFETY DEVICE | W.L. |
| CLOSED | Openstheleaforleaves | Noeffect | Noeffect (OPEN-Adisabled) | Noeffect (OPEN-Adisabled) | Noeffect (OPEN-Bdisabled) | Noeffect (OPEN-Adisabled) | OFF |
| OPEN | Noeffect | Closestheleaves orleaf | Noeffect (OPEN-Bdisabled) | Noeffect (OPEN-Adisabled) | Noeffect (OPEN-Bdisabled) | Noeffect (OPENBdisabled) | lighted |
| AT CLOSING | Stopsoperation |  | Stopsoperation | Noeffect | Stopsoperation (OPEN-Bdisabled) | Stopsoperation (OPEN-A/Bdisabled) | flashing |
| ATOPENING |  | Stopsoperation |  | Stopsoperation (OPEN-Adisabled) | Noeffect | $\begin{gathered} \text { Stopsoperation } \\ \text { (OPEN-A/Bdisabled) } \end{gathered}$ | lighted |

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[^0]:    (1) If maintained, it prolongs the pause until disabled by the command (timer function) NB.: Effects on other active pulse inputs in brackets.

